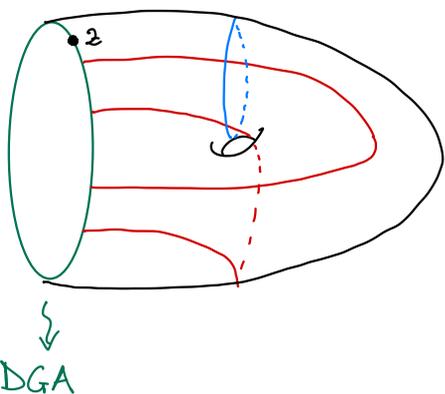


3. Straud Algebras

① CHORD DIAGRAMS



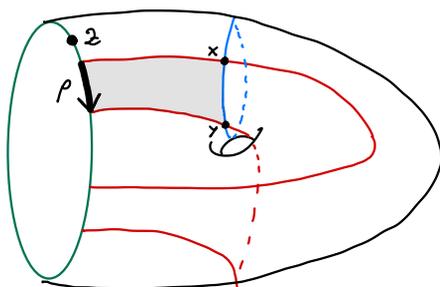
Consider the half-Heegaard diagram on the left.

The boundary is a circle w/ a basepoint z and pairs of matched circles.

We define a DGA associated to it with a two-fold objective:

- 1) in constructing a generator of $\widehat{CF}(H)$, we want to remember which curves are already occupied; *no idempotents* [recall that each generator is a type of intersection points s.t. there is exactly one on each α (and on each β) curve]
- 2) remember how the partial domains meet the boundary, and if you can glue them to partial domains on the other side.

e.g.

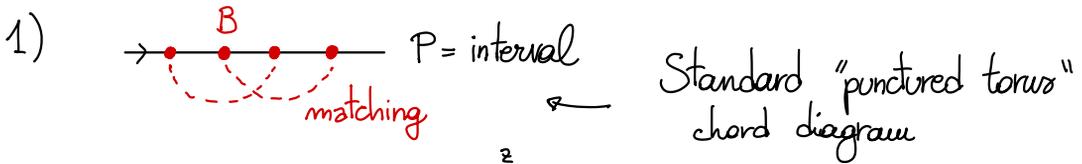


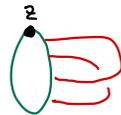
no strands

Def: A CHORD DIAGRAM \mathcal{Z} consists of

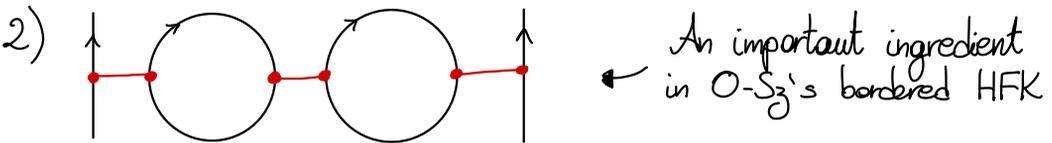
- a cpt oriented 1-mfld P
- a finite set $B \subseteq P$, and
- a fixed-pt-free involution $\varphi: B \rightarrow B$ (the MATCHING).

The contractible connected components of P are called LINEAR BACKBONES, the other ones CIRCULAR BACKBONES.

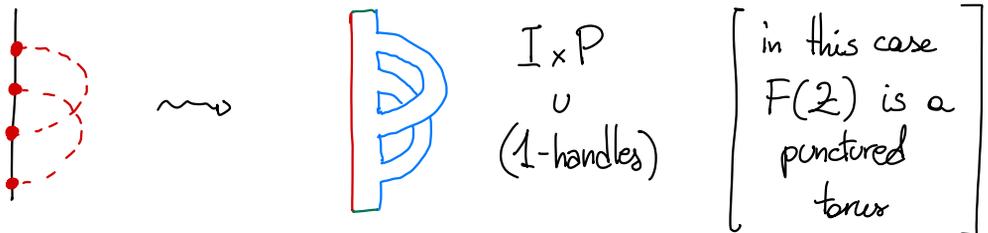


RK: It's obtained from  (the boundary of the previous half Heegaard diagram) by cutting along z .

The diagram shows a vertical line with a red arc on its right side. A horizontal line labeled 'z' passes through the top of the red arc.



RK: Chord diagram $\mathcal{Z} \rightsquigarrow$ surface w/ partitioned boundary $F(\mathcal{Z})$ (sutured surface)

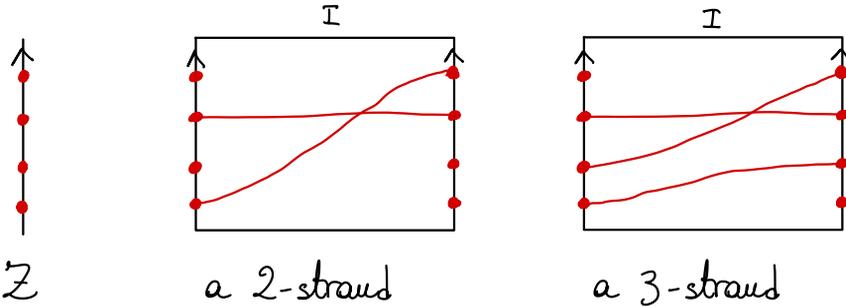


② PRE-STRAND ALGEBRA

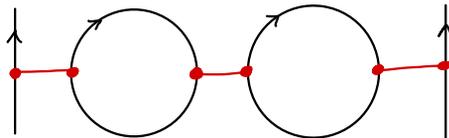
Def: A K-STRAND $s = \{s_1, \dots, s_k\}$ on a chord diagram Z is a collection of smooth functions $s_i: I \rightarrow P$ s.t.

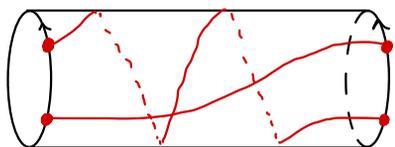
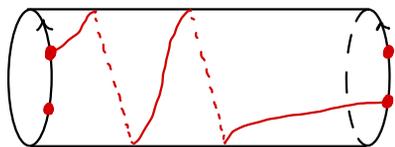
-) $s(0) = \{s_1(0), \dots, s_k(0)\}$ (resp. $s(1) = \{s_1(1), \dots, s_k(1)\}$) consists of k distinct points in B , and
-) each s_i has constant, non-negative speed, i.e. $\frac{ds_i}{dt} = \alpha_i \geq 0$.
used to choose a canonical representative

1) Examples of K -strands on the punctured torus chord diagram.

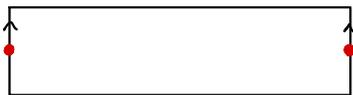
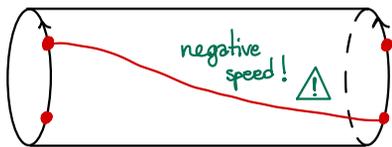
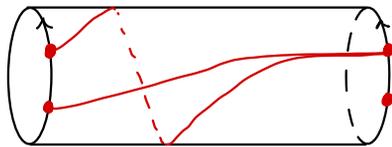
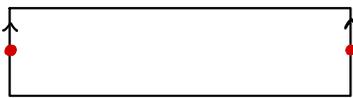


2) Examples on the chord diagram





a 4-strand

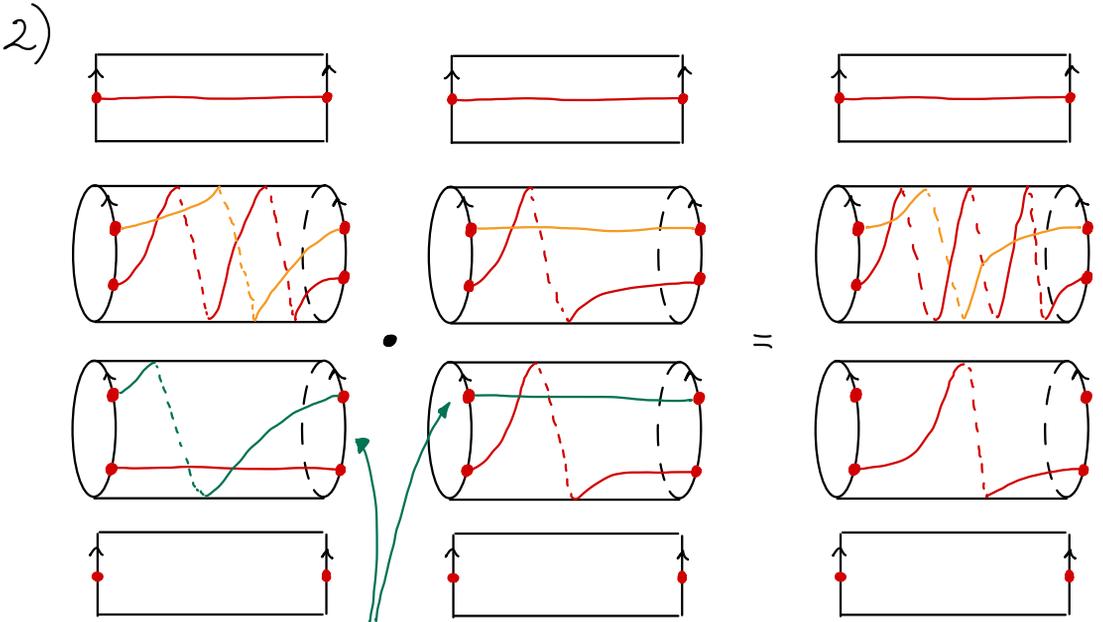
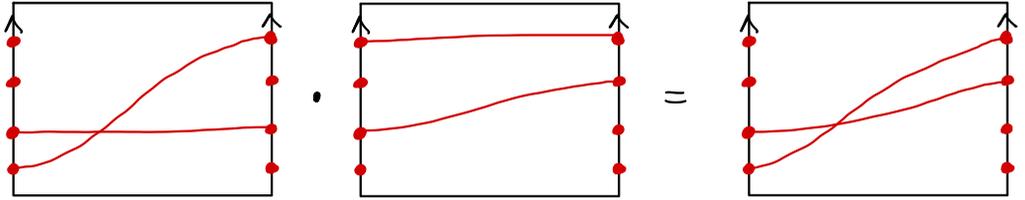
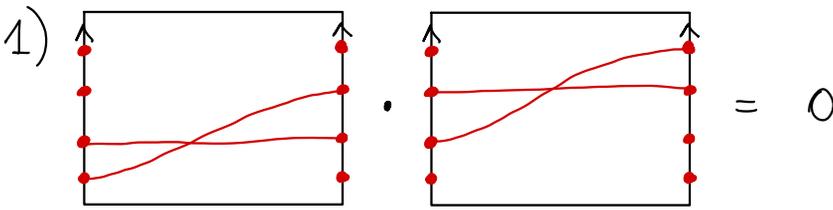


NOT a k-strand

Multiplication

Def: Let $\tilde{\mathcal{A}}(\mathcal{Z}, k)$ be the \mathbb{F}_2 -vector space freely generated by k -strands on \mathcal{Z} . Given two k -strands s and t , we define $s \cdot t$ as follows:

- if $s(1) \neq t(0)$, $s \cdot t = 0$ (the strands are not concatenable);
- if the concatenation (after smoothing) contains a bigou, then we set $s \cdot t = 0$;
- in all other cases, $s \cdot t$ is the concatenation, properly rescaled.



if you add the
green strands you
get a bigon

To get a nonzero element you need to concatenate the strand that winds the most with the strand that winds the most.

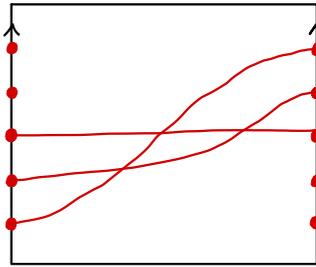
Differential

Def: for s a k -strand, we define ∂s as the of all k -strands obtained by resolving a crossing of s without producing a bigon, properly rescaled.

Extend linearly to a map

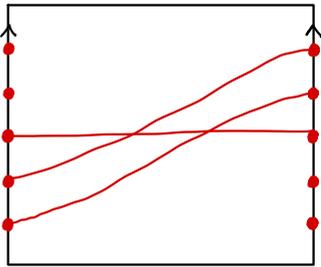
$$\partial: \tilde{A}(Z, k) \rightarrow \tilde{A}(Z, k)$$

1)

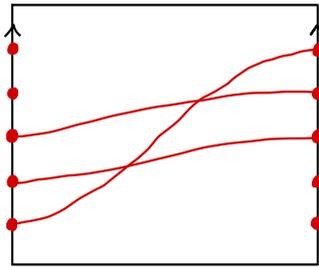


added an extra lpt to exemplify bigon (cannot be a chord diagram b/c $|B|$ is odd)

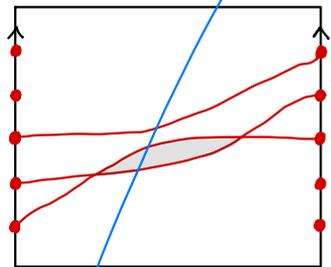
$\downarrow \partial$



+

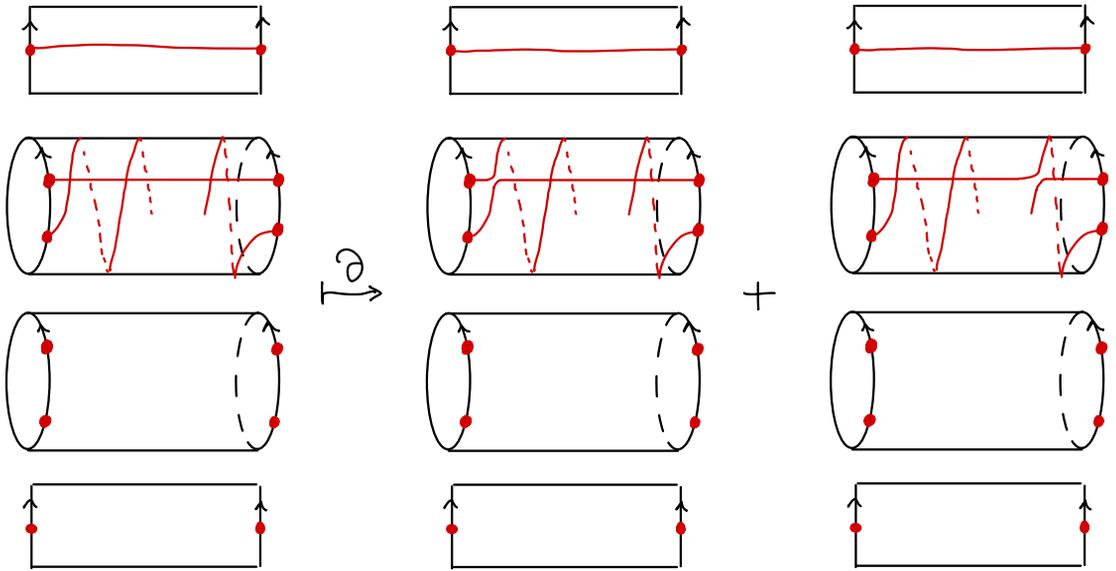


+



(contains bigon)

2)



(resolving all the other crossings in the middle creates bigaus)

Lemma: $\partial^2 = 0$

Pf: If we ignore the bigaus, we get

$$\partial^2 s = \sum_{\substack{(c_1, c_2) \text{ distinct} \\ \text{crossings}}} \text{resolution of } s \text{ at } c_1 \text{ and } c_2$$

which is obviously $0 \pmod{2}$.

We just need to check that $\partial t = 0$ in $\tilde{A}(\mathbb{Z}, k)$ if t contains bigaus.

If t contains exactly 1 bigou, then the two resolutions at the vertices of the bigou cancel out, and the others still contain a bigou.

If t contains ≥ 2 bigous, e.g. , then any resolution still contains bigous, so it is 0 in the algebra. \square

Thm: $\tilde{A}(\mathbb{Z}, k)$ is a DG algebra, called the PRE-STRANDS ALGEBRA.

Pf: Exercise. [Find unit and check Leibnitz rule.]

Rk: So far we have not used the matching on \mathbb{Z} .

③ STRANDS ALGEBRA

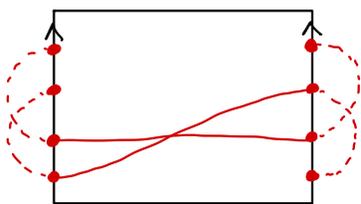
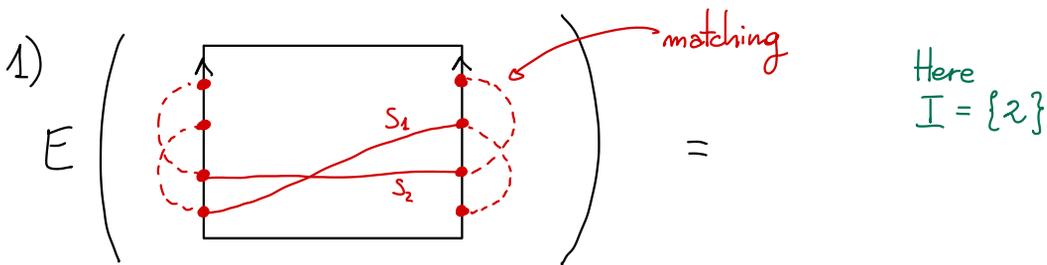
Def: Let $s = \{s_1, \dots, s_k\}$ be a K -strand on \mathbb{Z} , and let I denote the set of indices for which s_i is constant.

For $\mathcal{L} \subseteq I$, define $s^{\mathcal{L}} = \{s_1^{\mathcal{L}}, \dots, s_k^{\mathcal{L}}\}$ as the K -strand s.t.:

- for $i \notin \mathcal{L}$, $s_i^{\mathcal{L}} = s_i$;
- for $i \in \mathcal{L}$, $s_i^{\mathcal{L}}$ is the constant strand at $\varphi(s_i(0))$.

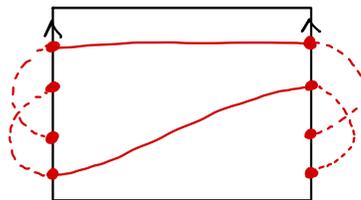
Then, the EQUALISER of s is

$$E(s) := \begin{cases} \sum_{\mathcal{L} \subseteq I} s^{\mathcal{L}} & \text{if } s(0) \cap \varphi(s(0)) = \emptyset = s(1) \cap \varphi(s(1)) \\ 0 & \text{otherwise} \end{cases}$$



$\mathcal{L} = \emptyset$

+

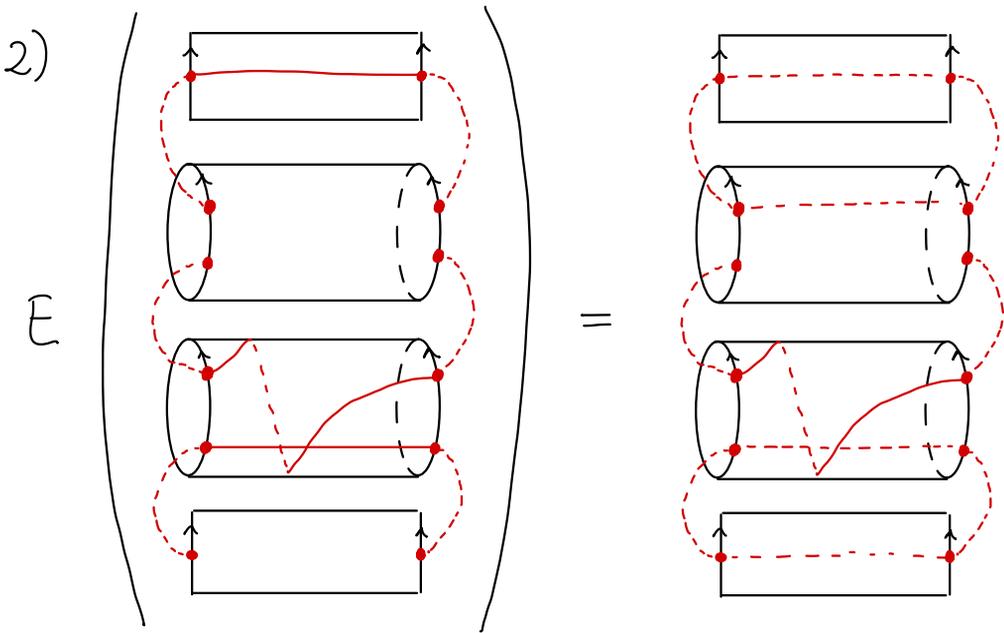


$\mathcal{L} = \{2\}$

$$E \left(\begin{array}{c} \text{Diagram 1} \end{array} \right) = \text{sum of 4 terms}$$

Notation: Replace all constant strands with dashed lines & also add dashed lines at the matched basepoints.

$$\begin{array}{c}
 \text{Diagram 1} \\
 = \\
 E \left(\begin{array}{c} \text{Diagram 2} \\ \text{Diagram 3} \end{array} \right) \\
 = \\
 \text{Diagram 4} + \text{Diagram 5}
 \end{array}$$



This element is the sum of 4 3-strands.

RK: $E \left(\begin{array}{c} \uparrow \\ \uparrow \\ \uparrow \\ \uparrow \end{array} \right) = 0$

The diagram shows the evaluation of the element E on a specific input. The input is a 4-strand braid with four strands, each with an upward arrow. The top and bottom strands are straight. The middle two strands are connected by a braid. The evaluation is shown as a sum of four terms, each with a different braid configuration for the middle two strands. The result is 0.

because $s(1) \cap \varphi(s(1)) \neq \emptyset$.

From the dashed notation it is clearer.

Def: The STRANDS ALGEBRA $\mathcal{A}(\mathbb{Z}, \mathbb{K})$ is the \mathbb{F}_2 -vector subspace of $\tilde{\mathcal{A}}(\mathbb{Z}, \mathbb{K})$ spanned by the equalisers.

Lemma: $\mathcal{A}(\mathbb{Z}, \mathbb{K})$ is closed under multiplication and differential.

Proof: Multiplication

$$E(s) \cdot E(t) = \left(\sum_{l \in I} s^l \right) \cdot \left(\sum_{l' \in I'} t^{l'} \right)$$

Suppose $\exists l, l'$ such that $s^l(1) = t^{l'}(0)$, and choose

If $E(s) \cdot E(t) \neq 0$, $\exists l, l'$ such that $s^l(1) = t^{l'}(0)$, and replace s and t with s^l and $t^{l'}$ respectively (equalizers do not change).

Then,

$$\begin{aligned} E(s) \cdot E(t) &= \left(\sum_{l \in I} s^l \right) \cdot \left(\sum_{l' \in I'} t^{l'} \right) \\ &= \sum_{l \in I \cap I'} \underbrace{s^l \cdot t^{l'}} \\ &= \sum_{l \in I \cap I'} (s \cdot t)^l = E(s \cdot t) \end{aligned}$$

concatenable iff you change the endpoints in the same way

contains a bigon iff $s \cdot t$ does

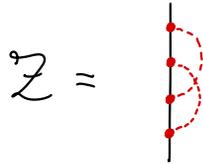
Differential: consider $\partial(E(s))$.

- *) If you resolve crossings away from constant strands you get equalizers.
- *) If you resolve a crossing involving a constant strand and a (necessarily) non-constant one, remove the matched constant lines; note the new lines created cannot be constant.

If bigons appear in one resolution, they are there for all the summands of the corresponding equaliser, because bigons cannot involve constant strands. □

RK: $A(\mathbb{Z}, k)$ is not a subalgebra of $\tilde{A}(\mathbb{Z}, k)$ because $1_{\tilde{A}(\mathbb{Z}, k)} \notin A(\mathbb{Z}, k)$. However, $A(\mathbb{Z}, k)$ has its own unit.

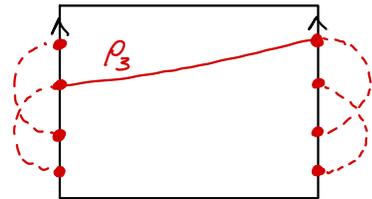
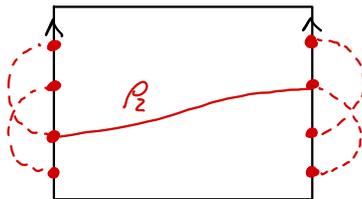
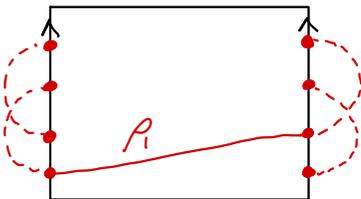
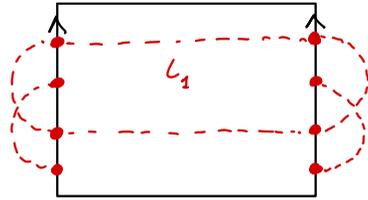
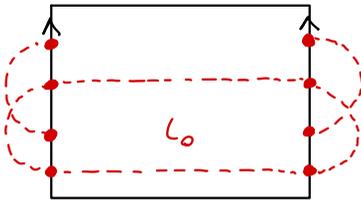
The torus algebra

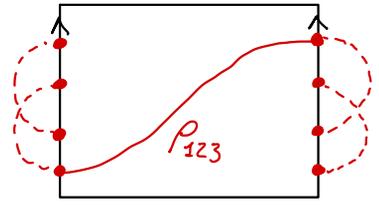
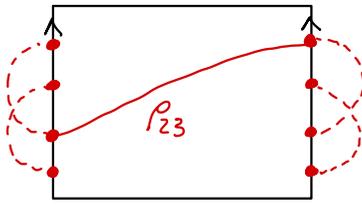
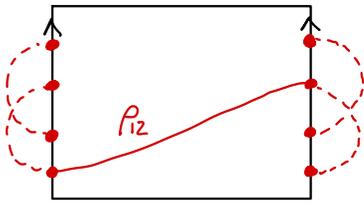


$A(\mathbb{Z}, 0) = \mathbb{F}_2$

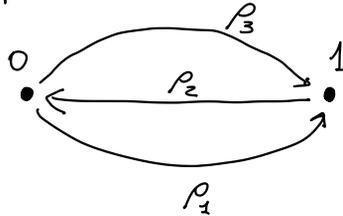
as a vector space

$A(\mathbb{Z}, 1) \cong \mathbb{F}_2 \langle L_0, L_1, P_1, P_2, P_3, P_{12}, P_{23}, P_{123} \rangle$





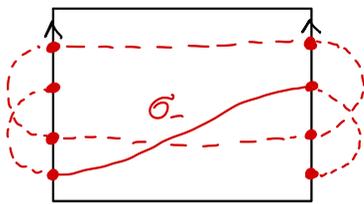
As an algebra, $A(\mathbb{Z}, 1)$ is isomorphic to the PATH ALGEBRA over the directed graph



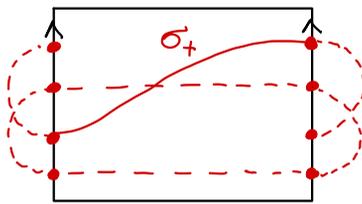
modulo the relations $p_2 p_1 = p_3 p_2 = 0$.

[ι_0 and ι_1 are the constant paths at the corresponding vertices.]

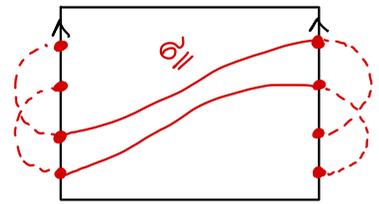
$$\underline{A(\mathbb{Z}, 2)} \cong \mathbb{F}_2 \langle \overset{\text{idempotent}}{\iota}, \sigma_-, \sigma_+, \sigma_{//}, \tau_-, \tau_+, \tau_x \rangle$$



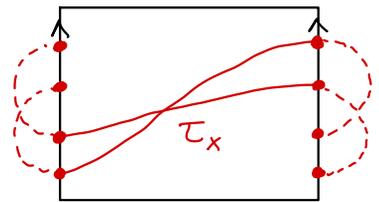
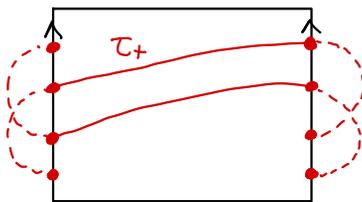
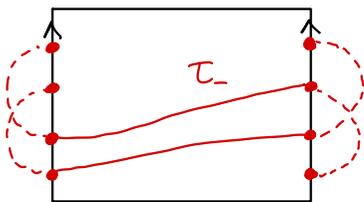
$\Downarrow \partial$



$\Downarrow \partial$



$\Downarrow \partial$



Exercise: $H_*(\mathcal{A}(\mathcal{Z}, 2)) \cong \mathbb{F}_2$, so $\mathcal{A}(\mathcal{Z}, 2)$ is quasi-isom. to $\mathcal{A}(\mathcal{Z}, 0)$.

④ IDEMPOTENTS and UNIT

Let $\mathcal{Z} = (P, B, \varphi)$ be a chord diagram and let $x \subseteq B /_{(b \sim \varphi(b))}$ a subset of cardinality k .

Def: $I_x := E(\text{Const}_S)$, where $S \subseteq B$ is any lift of x .

Ex: 1) $\{I_x \mid x \subseteq B /_{\sim}, |x| = k\}$ are orthogonal idempotents in $\mathcal{A}(\mathcal{Z}, k)$.

2) All idempotents of $\mathcal{A}(\mathcal{Z}, k)$ form an abelian subring $I(\mathcal{Z}, k) \subseteq \mathcal{A}(\mathcal{Z}, k)$.

3) In fact, $\{I_x\}$ is a basis of the subring of idempotents $I(\mathcal{Z}, k) \subseteq \mathcal{A}(\mathcal{Z}, k)$, seen as an \mathbb{F}_2 -vector space.

Def: An idempotent $e \in \mathcal{A}$ is called MINIMAL if it cannot be decomposed as the sum of non-zero orthogonal idempotents.

Ex: Suppose that:

-) the idempotents of A form an abelian subring \mathcal{I} ; and
-) $\{I_i\}$ is a basis of orthogonal idempotents.

Then $\{I_i\} = \{\text{minimal idempotents of } A\}$.

This shows that the set $\{I_x\}$ is uniquely determined by the algebraic structure of $A(\mathbb{Z}, k)$.

Def: $1 := \sum_x I_x$ is the unit of $A(\mathbb{Z}, k)$.

Thm: $(A(\mathbb{Z}, k), \partial, \cdot, 1)$ is a unital DGA.

RK: As a vector space, we have a splitting

$$A(\mathbb{Z}, k) = \bigoplus_{x, y} I_x \cdot A(\mathbb{Z}, k) \cdot I_y$$

Moreover, ∂ respects this splitting, and

$$\bullet : (I_x \cdot A \cdot I_y) \times (I_y \cdot A \cdot I_z) \longrightarrow I_x \cdot A \cdot I_z$$

Note that in particular $\partial(I_x) = 0$.

Example: the torus algebra $\mathcal{A}(2, 1)$

There are two idempotents, e_0 and e_1 .

$$e_0 \cdot \mathcal{A} \cdot e_0 = \mathbb{F}_2 \langle \rho_0, \rho_{12} \rangle$$

$$e_1 \cdot \mathcal{A} \cdot e_1 = \mathbb{F}_2 \langle \rho_1, \rho_{23} \rangle$$

$$e_0 \cdot \mathcal{A} \cdot e_1 = \mathbb{F}_2 \langle \rho_1, \rho_3, \rho_{123} \rangle$$

$$e_1 \cdot \mathcal{A} \cdot e_0 = \mathbb{F}_2 \langle \rho_2 \rangle$$

DG category representation

We can form a category $\mathcal{C}_{\mathcal{A}(2, k)}$ by letting:

*) objects = minimal idempotents

*) $\text{Mor}(I_x, I_y) = I_x \cdot \mathcal{A} \cdot I_y$

diff. k -module

$[\text{Mod}_k^{\text{op}}$ is a monoidal category]

*) $\mathbb{1}_{\text{Mor}(I_x, I_x)} = I_x \cdot \mathbb{1}_{\mathcal{A}} \cdot I_x$

*) $0: \text{Mor}(I_y, I_z) \otimes \text{Mor}(I_x, I_y) \rightarrow \text{Mor}(I_x, I_z)$

$\mathcal{C}_{\mathcal{A}(2, k)}$ is a DG category (def: same as above + associativity & unity axioms).

RK: There are also A_{∞} -categories, but they are not categories (do not satisfy associativity & unit axioms).